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## Wi-Fi Sensing Algorithms Utilizing Zigbee RF Receiver for Use in Emergency Communications Mesh

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## **WI-FI SENSING ALGORITHMS UTILIZING ZIGBEE RF RECEIVER FOR USE IN EMERGENCY COMMUNICATIONS MESH**

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### **Abstract**

*This thesis examines a low-power Wi-Fi sensing wake-up controller for an emergency communications mesh network; the goal of the research study is to progressively develop a prototype system that could be used in a live environment. Wireless network protocols are reviewed, in addition to a limited view of cluster analysis, in order to introduce relevant receiver concepts crucial to understanding this study. Algorithms for system implementation are developed, and pseudocode, designed to be configurable and platform-independent, is given for each. The system's design goals are identified, followed by a discussion on approaches and optimizations in order to maximize the system's usefulness. An example hardware configuration is given, in conjunction with an analysis of benefits and a discussion of drawbacks for several design options. Finally, the prototype is tested according to design goals in order to establish its feasibility. The results demonstrate that the prototype meets the proposed design goals. The implications of these findings include low power optimization for wireless technologies and machine learning techniques for wireless detection.*

## **1. INTRODUCTION**

### **1.1 Problem**

A stable form of communication has moved from the realm of luxury to an expected standard that is considered necessary for modern living. This expectation has become exaggerated in recent years as most Americans have access to an internet-enabled mobile phone within a few feet of their person at all times. Physical road maps have even become superfluous as many phones have direct access to Global Positioning System (GPS) navigation. Mobile phones can often communicate regardless of cellular connectivity, as many of these devices can connect to any Wi-Fi hotspot and use a voice over internet-protocol (VOIP) application to speak with any other internet connected user. The robustness of the mobile phone as a communication device is indisputable; its presence bordering on ubiquity lends support to smartphones as a viable candidate for any communication in any scenario. However, in the event where a region is left without power for an extended period of time, mobile phones, as well as any other traditional forms of communication, are left crippled, if not useless. This scenario is a common occurrence during a natural disaster.

Natural disasters, such as floods, snowstorms, tornados, and hurricanes cause thousands of deaths around the globe each year, affecting nearly 211 million people per year (Young, Balluz, and Malilay 7). While many deaths occur as a direct result of the event itself, a much

larger portion occurs after the event, an anomaly which could be mitigated by a proper post-emergency communication infrastructure (Linnerooth-Bayer, Mechler, and Pflug 1044). For example, hurricane Katrina made landfall in the fall of 2005, and in a matter of hours she had left a majority of the gulf coast without power or communication, a situation that would not be remedied for several months. More recently, the Tohoku earthquake and resulting tsunami in Japan in 2011 left almost 4.4 million households without power for several days (Inajima and Okada 11). State of the art emergency communication generally occurs over satellite phone, which provides constant access to a reliable system but which suffers from the fact that the systems are costly, and only a small minority of people has access to them. Most emergency scenarios require the distribution of information such as alerts, warnings, and the location of shelters or sources of clean water; these tasks are monumental for the users of satellite phones.

Therefore, the need is readily apparent for the development of a reliable alternative emergency communications infrastructure that is capable of handling requests for a large group of clients. The production of any end-user system for distribution is unfeasible, as the cost for such a large deployment would be insurmountable, and the necessary distribution and training would create costs that would render the system useless. Thus, the system should either be a multiuser system at centralized locations, or immediately integrate with current end-user systems with little or no difficulty on the users' part.

As stated above, the ubiquity of communications by mobile phones, the predefined communication protocols, and the fact that users require no additional training, make mobile phones a prime target for the second option. An infrastructure that takes advantage of these preexisting conditions would maximize the resources at hand while adding no additional cost. These factors led to the decision to utilize a distributed mesh network that interfaces directly with end-user mobile phones. Since the communication protocol to these devices would be Wi-Fi, this infrastructure should also be able to interface with off-the-shelf laptops.

Unfortunately, the power consumption of a standard Wi-Fi radio ("1.65W, 1.4W, 1.15W, and .045W in transmit, receive, idle and sleep states respectively") is more than could be scavenged by current solar panels ( $\sim 10\text{mW}/\text{cm}^2$  outdoors at noon) unless the transceiver maintains a sleep state for long periods of time (Gupta and Mohapatra 124; Pei, Zingyu, and Xiaojun 641). However, network discoverability is impossible while the wireless access point is in sleep mode as it would render the system useless. An optimal solution then would be to keep the Wi-Fi radio in sleep mode until a user wishes to connect to the network, at which point the Wi-Fi radio is brought out of its sleep mode to establish a connection with the user.

### *1.2 Thesis Statement*

The goal of this research project is to develop a robust, solar powered emergency communications mesh network; this system will be designed to provide access to a standard Wi-Fi radio without exhausting the limited power available from the provided solar cells. To achieve this, a lower power radio called ZigBee, which communicates on the same frequency band (albeit a different interface), will be utilized to determine if a client is seeking Wi-Fi presence in a given area.

### *1.3 Approach*

The proposed system seeks to solve the issue of power management for the emergency mesh network. The major drain it seeks to replace is the power consumption of the Wi-Fi radio

during periods of inactivity. By placing the Wi-Fi radio into a sleep mode, that drain is reduced by a factor of 30. However, in this sleep mode, the access point cannot allow users to connect, nor sense if a user is attempting to connect. The system solves this divide by using a wake-up controller composed of a low-power PIC microcontroller and a ZigBee RF transceiver to determine if a user is seeking wireless access. The ZigBee radio consumes considerably less power than the Wi-Fi radio, maxing out at 76mW during a transmission when operating at 3.3V (Microchip<sup>®</sup> Technology Inc., 142). ZigBee and Wi-Fi, however, maintain entirely different physical layers despite transmitting data in the same frequency. Therefore, analysis must be performed on the received transmissions in order to determine if its source is a user seeking Wi-Fi access.

The signal analysis will be performed by utilizing a J48 tree, an implementation of an a priori cluster analysis which classifies data points based on statistical properties. The signal must be classified and its origin verified so that the system does not unnecessarily wake the Wi-Fi radio and waste scavenged energy. During active Wi-Fi communication, the ZigBee radio can be put to sleep, during which it consumes only 6.6 $\mu$ W when operating at 3.3V (Microchip<sup>®</sup> Technology Inc.142).

## **2. BACKGROUND**

### *2.1 Key Concepts*

The reader must understand wireless communications protocols 802.11 and 802.15.4 and limited aspects of a priori clustering algorithms in order to foster a thorough understanding of this research study. A short review of each is provided in the following sections.

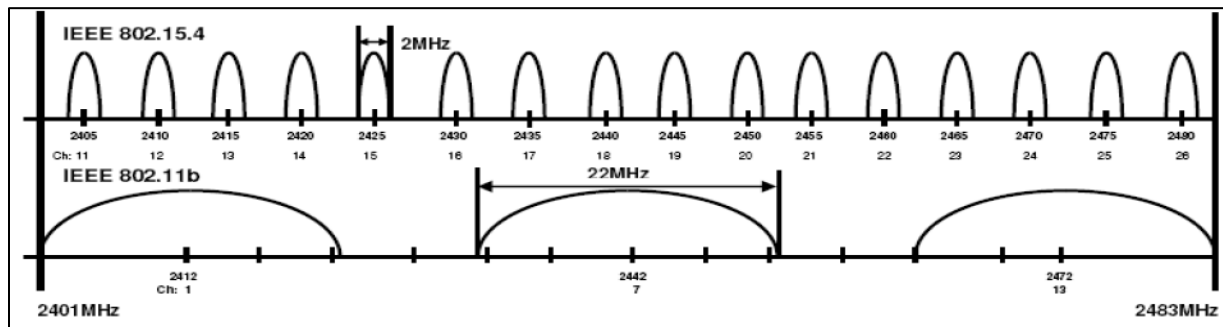
#### **2.1.1 802.11 (Wi-Fi) and 802.15.4 (ZigBee) Communications Protocols**

802.11 wireless communication protocol, more commonly referred to as Wi-Fi, is defined as the set of standards that sets forth the method in which data are transmitted between wireless radio transceivers. Wi-Fi communication exists in the 2.4 GHz frequency band utilizing special blends of frequency modulation called phase-shift keying in order to encode the binary representations of the data being sent. Wi-Fi “channels” are 22 MHz frequency bands in the spectrum encapsulating a single stream of communication. There are 14 channels in the 2.4 GHz range, the peaks of which are situated every 5 MHz (Villegas et al. 118-119). Most wireless access points (WAPs) communicate on one of four channels (1, 6, 11, and 14) which represent disparate non-overlapping channels, thus reducing noise between competing channels. Channel 14 is in licensed airspace in most countries, and therefore reserved for restricted applications.

Data are transmitted in “frames” of different types, each containing a subset of properties agreed upon as the current standard. Frames may be encrypted if security protocols such as WEP or WPA are enabled, which obfuscates the frame for all but the intended devices so that frames may not be read properly by any other listening client.

802.15.4 wireless communication protocol consists of unlicensed airspace that allows the user to define the upper layers of the protocol standards. ZigBee is one of several specific standards created within this protocol; it operates within several frequencies, primarily the 2.4 GHz range. ZigBee radio devices have the advantage of shifting from sleep mode to active mode in a short period of time (~15ms), allowing the transceiver to be both responsive and power efficient (Legg). ZigBee, when used as a means of communication, will attempt to transmit data on channels that correspond to the least amount of Wi-Fi interference by utilizing ZigBee

channels 15, 16, 21, 22, and 27 (if not in licensed airspace), which fall between Wi-Fi channels 1, 6, 11, and 14 respectively as seen in Figure 1 (Thonet et al. 7). These channels provide optimum signal strength and noise reduction for unlicensed airspace in the 2.4 GHz range. ZigBee channels occur every 5 MHz and each channel covers approximately 2 MHz. The physical layers of the two protocols are distinct; consequently one cannot read the contents of the other. However, the basis of this research study is dependent upon the fact that these two communication protocols overlap in frequency, and therefore have the ability to sample the same air space.



**Figure 1:** Comparison of Wi-Fi and ZigBee channel layout.

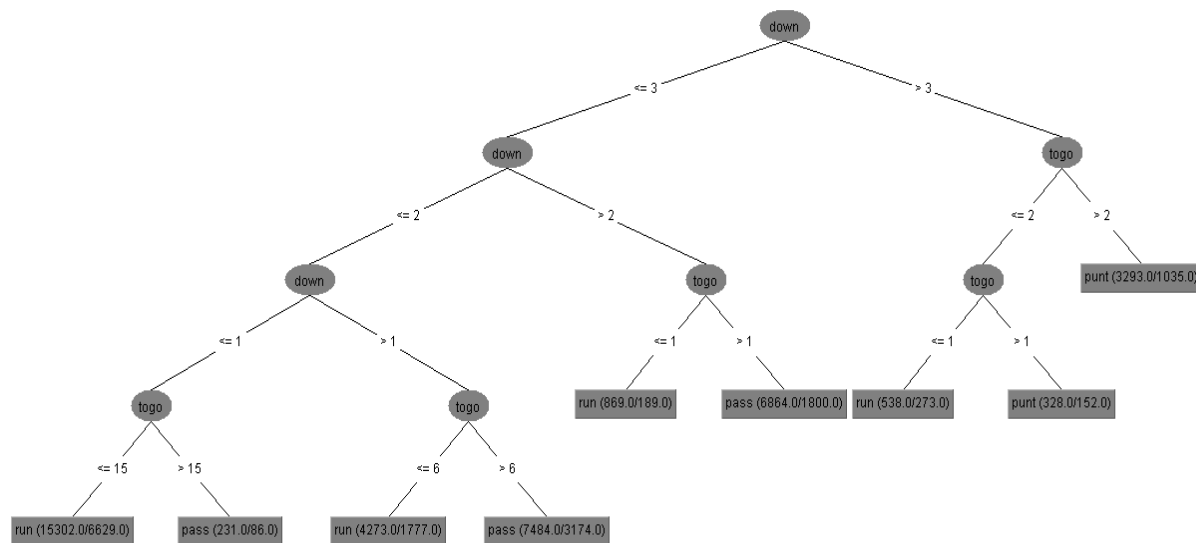
### 2.1.2 A priori Clustering Algorithms

Cluster analysis is defined as any statistical model that groups statistically alike data points into categories (Halkidi, Batistakis, and Vazirgiannis 3). These categories can then be modeled in order to provide analysis and assumptions about future data points. A priori clustering is defined as a set of clustering algorithms that uses predetermined nominal categories and training data in order to improve the statistical clusters, based on the statistical features gathered about the objects. The purpose of such algorithms is to provide adaptive computer systems that can make decisions, based upon a high statistical likelihood, without any further input from a user. The statistical data to be modeled against can be user-defined, or a large amount of statistical data can be sifted through to provide maximum accuracy. For instance, a clustering algorithm could be used to group similar people into categories so that, given a few data points concerning an individual, proper advertisements may be delivered to that individual, constituting an adaptive version of market research.

This algorithm used several instances of a priori clustering in order to determine a model of high statistical significance that would provide a responsive yet highly accurate formula for predicting the existence of a user seeking Wi-Fi access. The specific algorithm chosen for this application is the J48 decision tree implemented in Weka, a data mining tool. Decision trees are described by Bresfelean as follows:

Decision trees models are commonly used in data mining to examine the data and induce the tree and its rules that will be used to make predictions. The true purpose of the decision trees is to classify the data into distinct groups or branches that generate the strongest separation in the values of the dependent variable (Bresfelean 52).

A J48 decision tree is implemented using a set of training data points, and discriminating between them based on their given attributes. The algorithm uses the following structure in order to create the most distinctive tree. First, a decision is made on which attribute creates the most distinct split between the data. Then, for each created node, if all data points are not within the same category, a subtree is created that best divides the remaining data. Otherwise, the branch is terminated and the node is assigned to the category describing the data. This algorithm continues until there is no more ambiguity or no more attributes can be used in order to further separate the data. The latter case then assigns all leftover nodes to the category which best describes the data. Figure 2 provides an example of how a J48 tree can be used to determine future actions based on a known training set using data taken from the 2009 NFL season (Burke).



**Figure 2:** Example J48 tree demonstrating likelihood of actions based on training data.

## 2.2 Wi-Fi Interprotocol Cooperation and ZiFi

Several projects currently seek to increase the cooperation between distinct communication protocols in order to increase productivity in some manner. Projects like Esense, S-WOW and Wake on WLAN promote cooperation by direct communication between protocols; projects like ZiFi, Wake-On-Wireless, and Turducken promote a hands-off listening approach to provide information about networks in an effort to extend the lifetime of battery-powered clients (Chebrolu and Dhekne 85; Mishra, Chebrolu, and Raman 761, Mishra et al. 1; Shih, Bahl, and Sinclair 160; Sorber et al. 261; Zhou et al. 59).

### 2.2.1 Esense

Esense proposes a mode of communication between separate physical layers of communication protocols by creating a limited alphabet from the energy profile determined from the RSSI (received signal strength indicator) values scanned during a given frame. Using this method, the writers prove that a reliable paradigm of communication can be created. "Our results show that we could potentially create an alphabet size as high as 100; such a large alphabet size

promises efficient Esense communication” (Chebrolu and Dhekne 85). The drawbacks of such a project are that significant changes have to be created to end-devices using each protocol in order to accept such a language; it is therefore currently feasible only in specialized applications.

### **2.2.2 Zifi**

Zifi is an NSF-funded project that aims to utilize a ZigBee wake-up controller for mobile-phone or laptop users in order to save battery life, while constantly scanning for Wi-Fi access points. In essence, Zifi represents the exact opposite goal from what is proposed in this paper. The driving force behind Zifi is the constant drain that a Wi-Fi radio enacts on a mobile device during its active scanning period. In order to reduce this cost, a secondary low-power ZigBee radio is used to scan the frequency in order to determine the presence of Wi-Fi WAPs in the vicinity, and to wake up the Wi-Fi radio on the client device (typically a mobile phone or laptop). The process by which Zifi achieves its goal is detailed by Zhou et al.:

To capture Wi-Fi interference signatures, Zifi utilizes the received signal strength (RSS) indicator available on ZigBee-compliant radios. However, we observed that the statistics of Wi-Fi RSS samples, such as power magnitude, time duration, and inter-arrival gap, exhibit surprising resemblance with those of other RF sources, and hence provide little hint about the existence of Wi-Fi. Motivated by this observation, Zifi is designed to search for 802.11 beacon frames in RSS samples. Periodic beacon broadcasting is mandatory in Wi-Fi infrastructure networks and hence provides a reliable means to indicate Wi-Fi coverage (Zhou et al. 49-50).

Beacon broadcasting is the method that promotes Wi-Fi WAP discovery, wherein WAPs will release a periodic frame of a short duration containing a succinct homogeneous set of data. The energy signature created by beacon frames is easily spotted given a controlled environment. However, Zifi operates in a lively RF environment, and as a result the algorithm used must be more robust to noise. Zifi has the advantage that it may take longer for calculations as users are generally in a WAP’s range for an extended period of time, allowing the algorithm to use more data and complex arithmetic operations. The false negative rate is not as crucial for this application, as a false negative in Zifi represents a user missing the opportunity to utilize a Wi-Fi network; a false negative in the mesh network represents a potential survivor missing access to critical emergency information.

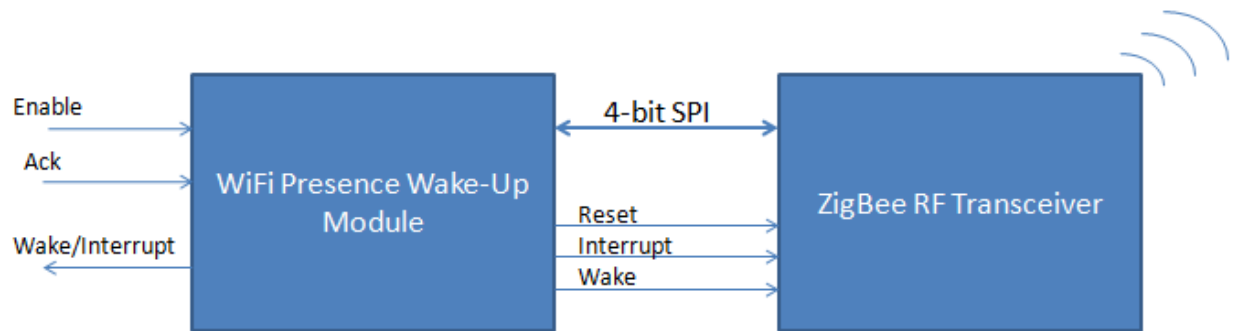
The algorithm developed utilizes a special variation of folding to determine Wi-Fi activity with an error rate of below 4.8%. The prototypes developed require additional hardware to be attached to the mobile phones or laptops, which increases power consumption and adds bulky external equipment. However, the goal is to extend this idea to a dedicated piece of hardware inside machines as a functional low-power wake up controller provided the transceiver can be integrated with current technologies.

## **3. ARCHITECTURE**

### **3.1 High Level Design - Hardware**

The design of the hardware is dependent upon two factors: whether or not the ZigBee module will also be used for communication, and whether or not the Wi-Fi sensing module will

be implemented as a canned-up piece of hardware acting specifically as a wake-up controller, or as software on the client device.

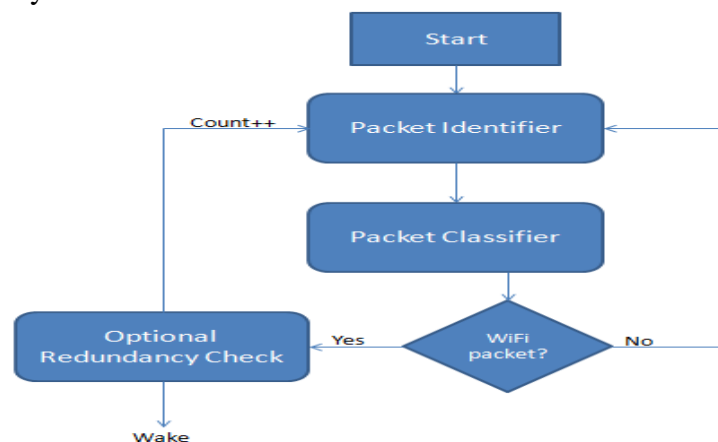


**Figure 3:** Hardware Specification for Wake-Up controller

Figure 3 provides an example of how the hardware could be configured. This setup assumes that the microcontroller used for sensing Wi-Fi activity is separate from the application. It also allows for interrupt driven behavior to be modeled using the Interrupt/Ack ports. The enable bit allows for the entire wake-up controller to be asleep while the main system is in use, while the wake-up function would allow the controller to wake up the main system upon Wi-Fi discovery. This hardware specification also keeps the ZigBee Transceiver separate so that the main system may also communicate with it using the SPI interface, or let it sleep when unused as the wake-up time for the ZigBee module is approximately 15ms.

### 3.2 High Level Design – Software

The software, then, is dependent upon how the hardware is specified, and whether or not the controller should act in an interrupt manner, or as a constantly updating value. The basic discovery algorithm is platform independent, and requires only the RSSI stream sent from the ZigBee transceiver. We will assume for this instance that the sensing module is a separate entity, and that it has full control of the RF Transceiver. The behavior of the output bits is dependent upon the platform; therefore, for this instance, we will assume a one bitput that is active high once Wi-Fi activity is determined.



**Figure 4:** High Level Algorithm Specification



The two main functions within this algorithm are the packet identifier method and the packet classifier method. These two methods take as input the RSSI data stream from the ZigBee module, transforming it into a recognizable data structure that is then classified according to the a priori clustering algorithm defined by the user; finally a determination is made on whether the packet is a Wi-Fi packet, a Bluetooth packet, a ZigBee packet, or noise. If the packet is determined to be a Wi-Fi packet, an optional redundancy check can be used to increase accuracy, but at the cost of speed and possibly causing a false negative result. This optional redundancy check can be defined by the user based on the parameters that are trying to be optimized.

### *3.3 Design*

As stated above, ZigBee communication generally occurs on a specific subset of channels in order to avoid the peaks created by Wi-Fi interference. However, if one were to attempt to sense active Wi-Fi access points or users searching for Wi-Fi access, one would instead listen on ZigBee channels correlated most closely with the peaks of Wi-Fi channels 1, 6, and 11. ZigBee channels 12, 18, and 25 would need to be scanned periodically to check for wireless activity. A lack of activity on these channels indicates that there is likely no Wi-Fi presence in the area. However, activity on these channels does not necessitate that there is an active WAP or user searching for Wi-Fi access. Other sources of noise (e.g. microwave radiation, Bluetooth, and other ZigBee components) can emit waves in this frequency, causing a false positive during which it would be a waste of scavenged energy to turn on the Wi-Fi antenna. As a result, cluster analysis was chosen to determine within a relative accuracy whether a given signal belongs to Wi-Fi or to some other signal or noise in the same frequency band.

#### **3.3.1 Initial Experimentation**

In order to process signal at a constant rate, a method native to the ZigBee module was utilized to calculate the signal strength throughout reception of a packet, and to store every signal sequentially on some external media so that a contiguous waveform could be generated. The ZigBee module must be tweaked to accept all packets, regardless of its ability to decode them, so that it can calculate signal strength of packets external to the ZigBee standard. In order to determine what waveforms corresponded to different sources of noise, controlled experiments were devised to block for all signals except the current source being analyzed. An unfortunate side-effect of the ubiquity of Wi-Fi Hotspots was the absolute inability to block for noise in an inhabited setting.

To meet this constraint, a faraday cage was created that could house the experiment in a signal free environment. The faraday cage is a 5' x 5' x 7' structure that is wrapped entirely in brass wire mesh in a continuous conductive sheet so that no signal in the spectrum can penetrate its surface. In order to increase its portability, each face is disconnected from the whole, but is held together by hinge clamps. The electrical continuity is preserved by wrapping the brass mesh to the inside of each contact point, and filling the void with a copper braid that expands to fill the width. In trial, with two layers of brass mesh, the faraday cage was found to completely attenuate all but the strongest signals in the 2.4 GHz range, and attenuate even a WAP in direct line of sight to almost unrecognizable noise. Removing this WAP allowed for complete radio silence in the testing environment.

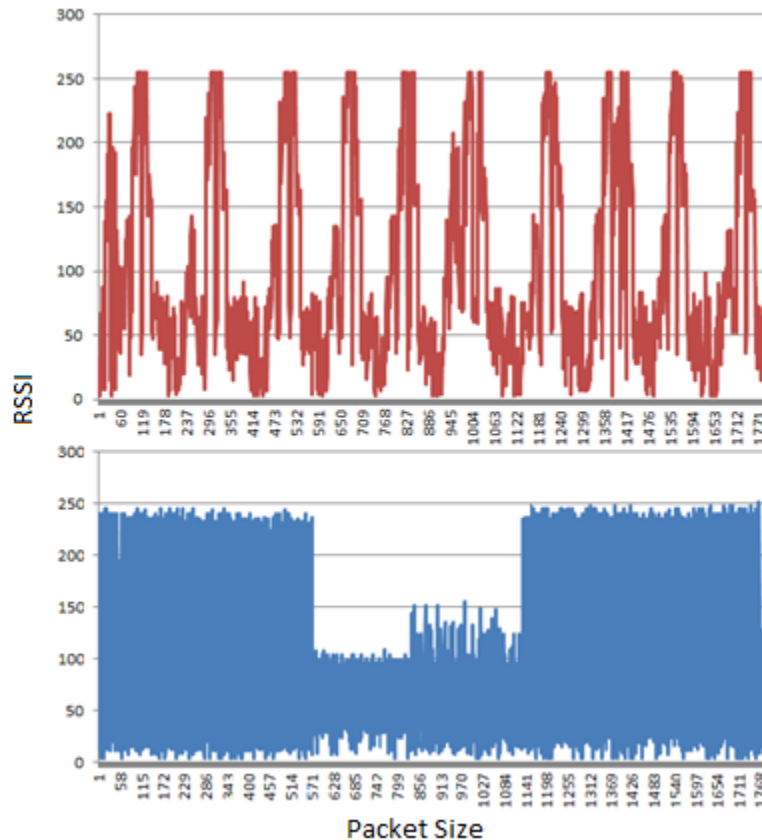


**Figure 5:** Faraday cage used in experimentation

While it is industry standard that WAPs will emit a beacon frame periodically in order to signal its availability, and that these frames are mostly identical in their energy signature, the same fact was not initially known for clients searching for wireless access. It seemed logical that a client could simply passively listen for beacon frames that correspond to available access points and then offer the user the ability to connect if desired. This scenario would have rendered this algorithm unfeasible because it is unlikely that the average end-user would be able to deploy a WAP in an emergency scenario where such a system is needed for communication.

Experiments were then developed to send a constant Wi-Fi scanning signal in order to emulate a user searching for an active WAP. Several preexisting Android Apps were utilized during this process, including WiFiScanner by PinApps and Wi-Fi Analyzer by Kevin Yuan. Originally, Wireshark was utilized to capture all packets to determine if there was any client structure similar to the beacon frame. Initial scans did not detect any activity; however allowing Wireshark to collect packets in promiscuous mode demonstrated that a repetitive packet of short duration was emitted by each of the client devices used in testing.

In order to visualize the energy signature of these discovered waveforms, each packet was collected by the ZigBee module and sent by a serial RS232 interface to a computer that cataloged the data. Each trial included 4,000,000 data points being collected in sequence, which included the time and the signal strength of each scan. This experiment was repeated for Bluetooth to gain access to a similar result set and the signals were compared. These experiments were reproduced using several end-devices, including mobile-phones from several different manufacturers, and recent market laptops with Bluetooth and WiFi connectivity.



**Figure 6:** Comparison of Wi-Fi and Bluetooth RSSI energy signatures

Wi-Fi signal in scanning mode consists of a regular periodic waveform with a slim profile whereas Bluetooth is a much longer, blockier waveform as shown in Figure 6. At this point, it became apparent that the statistical properties of individual waveforms of different protocols were likely to provide an easy schism that could be clustered against in order to provide an interface for simple protocol determination of future packets.

### 3.3.2 Packet Identification Algorithm

To perform the clustering algorithms, it is necessary to have some amount of statistical data about the waveforms in order to classify them. The statistical features originally determined to be clustered on included the standard deviation of a wave, the wavelength, and the time between waveforms. In order to determine distinct waveforms from a continuous signal stream, a method was created to check the Received Signal Strength Indicator (RSSI) throughout transmission of a packet and end capturing the waveform when the RSSI had remained below 75% of the maximum value found within the wave for an extended period of time. This method separated waveforms with a decent accuracy in a controlled environment, but a number of 0 values read during each wave periodically caused the algorithm to fail, often dividing waveforms into pieces, and significantly reducing the accuracy of the statistical data. Therefore, as each packet was scavenged, the 0 values were stripped, leaving only significant data points. As the 0 values were randomly distributed over a multitude of values, stripping them did not cause any

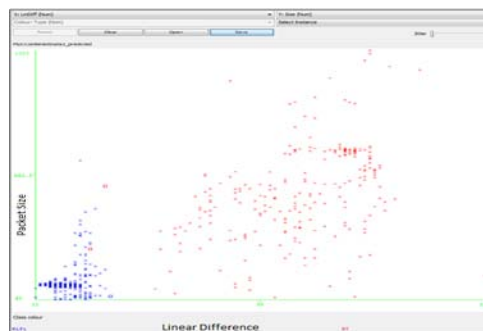
negative effect on packet size or standard deviation, but rather smoothed the waveforms, allowing for better analysis.

Additionally, in attempting to create distinct values for wavelength and for time between graphs, it became difficult to determine precisely when to start and end each waveform. A sudden noise spike could create several data points and trigger the start of a waveform erroneously. Similarly, determining when a waveform had run its course and contained no additional data was an imprecise process that could result in lost accuracy. As a result, it was determined to combine the wavelength and dead time statistics, as each wave was periodic in nature; adding the dead time into the wavelength standardizes each waveform with short tail periods before and after each wave. While not optimal, combining the two statistics does not dramatically reduce the responsiveness of the algorithm; however, depending on the strength and timing of interference, this may skew the results of the first Wi-Fi frame in a sequence, causing it to be recognized as noise.

The packet identification algorithm was performed on the gathered training data for both Bluetooth and Wi-Fi, and the results were then used in the development of the Packet Classification Algorithm. The identification algorithm is also used in the Wi-Fi wake-up module in a modified capacity using a linear difference statistic as opposed to the standard deviation for reduced calculation time and reduced memory requirement. Analysis of the training set showed that the linear difference increased accuracy as detailed in the results section.

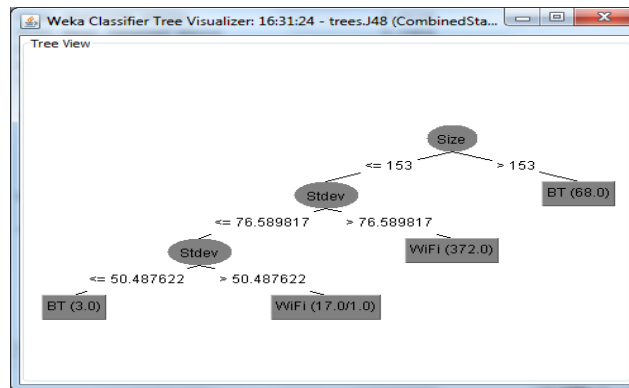
### 3.3.3 Packet Classification Algorithm

Once a packet has been successfully parsed from the energy stream, its statistical properties must be determined so that it can be classified according to the cluster analysis algorithm. Breakdown of the waveforms showed that Wi-Fi waveforms were generally less than 300 data points in size (corresponding to approximately 0.5ms) and had a standard deviation of RSSI between 74 and 80 when using the byte representation of the signal strength, which can be found on pages 95-96 on the datasheet for the ZigBee module (Microchip<sup>®</sup> Technology Inc.). Bluetooth, however, had wave sizes generally between 600 and 1500 data points (~1ms – 2.5ms) and an RSSI standard deviation between 54 and 78. This split has some amount of overlap in standard deviation, but a clear cut division in wave size. A combination of the two provided approximately a 95% accurate split in the training set using a J48 decision tree implemented in the Weka data mining tool (Figures 7 and 8).



**Figure 7:** Wi-Fi and Bluetooth waveforms visualized by linear difference and wave size

Standard deviation requires storing a large amount of data for each wave, and thus, a linear difference  $((\sum(|SignalStrength - PreviousStrength|)) / (WaveSize - 1))$  was used to accommodate for the limited stack sizes provided by microchip embedded systems. This result provided an improved split at an extremely reduced time and memory necessary. For the training data, Wi-Fi maintained a linear difference under 26, while Bluetooth was consistently above 30 with a median closer to 65. The J48 tree for the training set, using a linear difference modifier, produced a 99% accurate split.



**Figure 8:** J48 tree generated by Weka Classifier using Standard Deviation and packet size

### 3.4 Implementation

In order to create the system described above, a prototype was developed using a low power PIC microcontroller with a built-in SPI interface and several general I/O pins. The ZigBee transceiver used was the MRF24J40, which provides a detailed datasheet for ease of use purposes. The MiWi ZigBee stack was leveraged using the MCC18 compiler available through Microchip in order to easily interface with the ZigBee transceiver (Flowers and Yang 1-18). Utilizing the C compiler also allowed for quicker code creation in a testing environment as the algorithms were not established until late in the experimentation phase. The algorithms described above were implemented using C syntax for the pseudo code described in the next section.

#### 3.4.1 Packet Identification Pseudocode

This algorithm runs through the entire RSSI stream, determining where to distinguish individual waveforms. Input variables are: the RSSI stream, which may be read in the algorithm in real time directly from the ZigBee module in a live system, tailSize, which represents the number of packets read below the threshold before terminating the current waveform, and Thresh, a decimal value between 0 and 1 which adjusts the threshold to different levels of sensitivity. For the prototype, tailSize was set to 30 while Thresh was maintained at 0.75. The output is comprised of two integer arrays which give the start and end packets of each successive waveform.

```

PacketIdentify (int[] RSSI, int tailSize, float Thresh,
               int[] &Start, int[] &End){
    int i = 0;
    int start = 0;
    for each(RSSI){
        int Max = 0;
        int count = 0;
        int belowThreshCount = 0;
        while(belowThreshCount < tailSize){
            if(RSSI[count] > Max) Max = RSSI[count];
            if(RSSI[count] < (Thresh)Max)
                belowThreshCount++;
            else
                belowThreshCount=0;
            count++;
        }
        Start[i]=start;
        End[i]=start+count;
        Start += count;
        Start++;
    }
}

```

### 3.4.2 Packet Classification Pseudocode

This algorithm determines whether or not a given frame is a Wi-Fi frame. The input variables are: the RSSI stream for the frame, determined by the Packet Identification algorithm, the linear difference threshold, an integer value determined by the J48 cluster analysis, and the packet size threshold, also determined by the J48 tree. These threshold values are left as input variables instead of constants because the packet size is dependent upon the clock frequencies of the microcontroller and the ZigBee transceiver, while the linear difference is dependent upon the unit used in determining the RSSI. While the methods utilized in this paper were implemented using the byte representation of the RSSI determined by the ZigBee transceiver so that redundant conversions would be avoided, the actual unit for RSSI is dBm (decibels referenced to one milliwatt). The output value is simply a Boolean value that determines whether or not the received frame belongs to a Wi-Fi radio.

Bottom threshold values can be used to guard against noise and therefore decrease the false positive rate. However, in experimentation, noise packets were rarely below the Wi-Fi threshold values, but a partial Wi-Fi frame could easily be below the packet size threshold. Rather than conducting an analysis at this point to reduce false positives, a redundancy check was used to determine whether an individual was searching for wireless access. This was implemented as a state machine, with a positive value only being produced with three consecutive Wi-Fi frames or four Wi-Fi frames out of five consecutive frames.

```

PacketClassify(int[] PacketRSSI, int linDiffThresh,
    int packetSizeThresh, bool &isWiFi){
    isWiFi=false;
    int packetSize = 1;
    int linDiff = 0;
    for(int i=1; i<RSSI.size(); i++){
        packetSize++;
        linDiff += (RSSI[packetSize]-RSSI[packetSize-1]);
    }
    linDiff /= (packetSize-1);
    if(linDiff < linDiffThresh)
        if(packetSize < packetSizeThresh)
            isWiFi=true;
}

```

#### 4. METHODOLOGY, RESULTS AND ANALYSIS

The prototype developed through experimentation had several specific design goals that were necessary to meet. First, the system needed to be responsive. The window of opportunity to connect to a user may be relatively small, and the start-up time for the Wi-Fi radio interface represents a majority of the overhead. Second, the system needed to be low power. This was achieved by use of the ZigBee radio interface and a low-power microcontroller, and keeping the Wi-Fi interface asleep as often as possible. Lastly, the system needed to limit false negatives, as the main goal of the mesh network is to distribute emergency information to users. If a user cannot discover the network, then the system fails in its goal. This was achieved by accepting frames with lower precision, but maintaining accuracy by conducting a redundancy check. This functionality was chosen due to the periodic nature of the Wi-Fi waveform, allowing the system to take a slight reduction on speed in order to maintain accuracy and avoid false negative responses. The system above was developed with these parameters in mind.

##### 4.1 Methodology

In order to test the system described, two testing procedures were developed. For the first test, a program was created for the microcontroller which would display an LED when the system detected Wi-Fi, display a separate LED when the system detected Bluetooth, and display no LEDs when the system detected indeterminate noise or radio silence. This test was developed in order to demonstrate whether the system could still detect Wi-Fi in the presence of other sources of interference.

The second test was a specifically numerical test in order to determine the speed of the algorithm in practice. In order to achieve this, the detection algorithm sent a signal through the serial interface upon receipt of the first non-zero data point, and then a second signal was sent upon determination of Wi-Fi activity. A program was developed in Processing that would receive these signals and timestamp the receipt of each as a comma separated pair so that the difference could be calculated. The trial was run in a controlled environment with one end-user device constantly scanning for wireless access. This was repeated for 1000 iterations of the algorithm in order to maximize the accuracy of the statistical data.

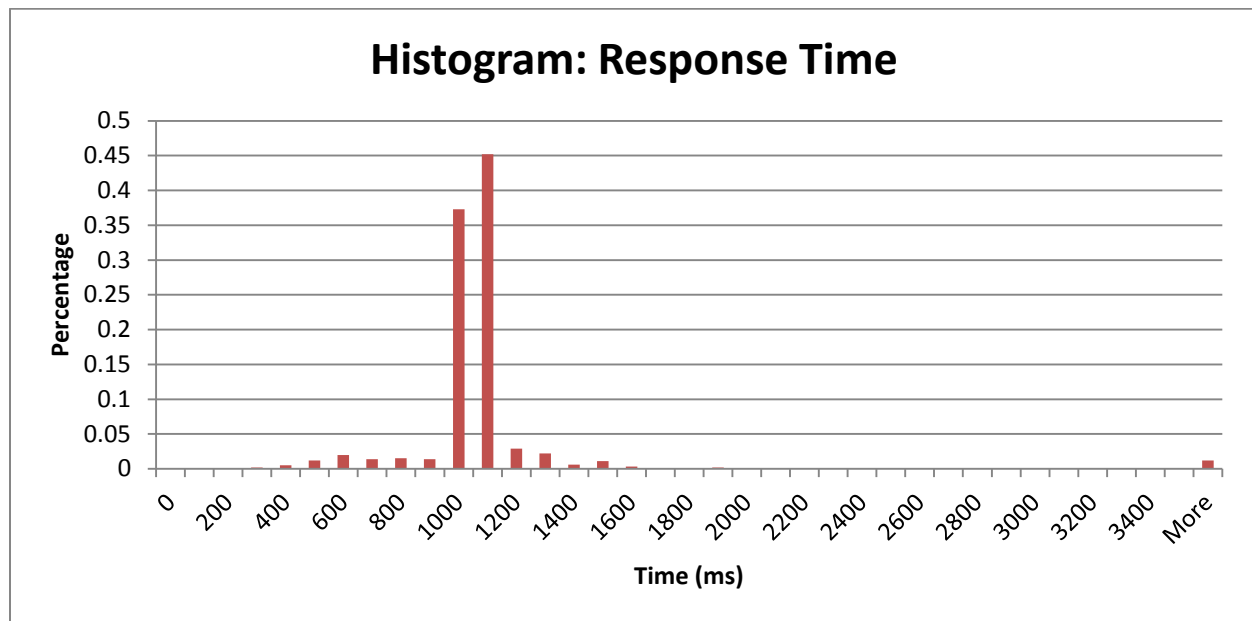
#### 4.2 Results

The first test proved the accuracy and robustness of the system in a noisy environment; it visually demonstrated that the system could determine the source of radio interference within a few seconds with several different end devices. The second test demonstrates the responsiveness of the system as a function of the speed. The following information was collected from the 1000 data points (all values are given in milliseconds):

**Table 1:** Statistical results of algorithm test

Maximum Value	21172
Minimum Value	172
Mean	1124.824
10% Trimmed Mean	1009.044
First Quartile	984
Median	1015
Third Quartile	1032
Standard Deviation	38.203

The following is a histogram of the data, showing the distribution of the response time in milliseconds.



**Figure 9:** Histogram displaying the frequency of the response time of the algorithm



### *4.3 Analysis*

The data above suggest that the algorithm will determine a user seeking Wi-Fi activity in approximately 1 second. Out of the 1000 trials, only 19 took longer than 2 seconds to determine access, and only 12 trials took more than 3.5 seconds. If one assumes that all 12 of those trials miss the set-up time required, resulting in a false negative, then the false negative rate in a controlled environment is 1.2 percent. This, in combination of a median response time of 1 second, meets the design goals provided.

These results demonstrate that the prototype system would act as a functional wake-up controller for the emergency mesh network. Further work is needed to properly obtain a false positive rate; however, the makeup of the radio space in an emergency scenario is unknown, and any testing environment would be speculative.

## **5. CONCLUSIONS**

### *5.1 Summary*

This research study introduces the concept of a Wi-Fi sensing wake-up controller, and develops a prototype for the system from proposed design specifications. 802.11 and 802.15.4 protocols are reviewed, as well as a priori cluster analysis in order to properly demonstrate the methods utilized for determining Wi-Fi activity. A prototype is then developed exploring the hardware and software options for the system. The hardware is discussed in a high level format, with analysis on several design options for system implementation. The software for the system is developed from a high level specification, and a sequential analysis of the creation of sensing algorithms is discussed and pseudocode is provided for implementations of each algorithm. The prototype system is then tested and analysis on the system is provided as a function of design goals.

The results demonstrate that the prototype system meets the design goals, while analysis is given on possible improvements to the system. The entire implementation is provided in a format that promotes user configuration since the system is application specific, and tweaks to the system are necessary in order to provide a configurable scheme for multiple applications.

### *5.2 Contributions and Potential Impact*

The major contribution of this system is as a power saving Wi-Fi sensing option for a proposed solar-powered emergency communications mesh network. This system is an integral part of that network, as a mesh node would quickly drain any scavenged energy using a standard Wi-Fi radio. Therefore, the potential impact of this thesis is developing a prototype which provides an interface allowing an emergency network to remain alive for a longer period of time, granting the ability to deliver critical information to more survivors; this is information that could save human lives.

The concepts developed within also serve as a proof of concept for possible social applications to be built on top of the mesh network provided. This will require some tweaking of the waveform selection methods, possibly the selection of more statistical features, in order to grant maximum accuracy in a high noise environment.

The prototype provided is but one specific implementation of the concept that was explored. As this specific use of a ZigBee transceiver as a wake-up controller for a WAP is application specific, the usefulness of the system developed outside of its intended purpose is limited. However, the ability to sense a frequency and determine the cause of signal can be

extended for several different interfaces. Using an approach similar to ZiFi, an integrated ZigBee module in a client device could act as a wake-up controller upon sensing Wi-Fi access or a client attempting to gain Bluetooth connectivity, thereby acting as a dual purpose battery-saving option. Combining this purpose with the ability to then communicate directly with SmartGrid devices within the home could be enough driving force to see a similar product implemented in consumer devices (Heile).

### *5.3 Future Work*

The primary branch of continued work on this project will be integrating it with the prototype mesh network to be deployed later this year. The hardware specification for the network has shifted since the beginning of this project, and therefore changes will need to be made to the wake-up controller in order to provide a shared interface to the ZigBee module, and to properly interface with the new microcontroller. After installation of the prototype, statistics can be gathered about the system's behavior in a live environment, which may detail changes needed to be made to the parameters of the algorithms in order maintain a more sensitive or less sensitive sensing interface.

Further work is needed to explore other implementations of similar sensing algorithms for other protocols, and to determine their feasibility as an interface for an end-user device. One possible implementation is the device described above which senses for Wi-Fi access or Bluetooth Clients, acting as a dual-purpose wake up controller. Allowing the ZigBee transceiver to interface with SmartGrid appliances for home-automation applications would further increase the usability of such a system. A prototype system that interfaces with current Smartphone showing the increased battery life and demonstrating connectivity with a SmartGrid application would be a step forward in producing consumer level electronics with a built in ZigBee interface.

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